

Kov.

$$E_n = \sum_{m=\emptyset}^{N-1} e_n^2(m)$$

$$\Phi_n(i, k) = \sum_{m=\emptyset}^{N-1} S_n(m, i) S_n(m, k)$$

$$\begin{bmatrix} \Phi_n(1, 1) & \dots & \Phi_n(1, p) \\ \vdots & & \vdots \\ \Phi_n(p, 1) & \dots & \Phi_n(p, p) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_p \end{bmatrix} = \begin{bmatrix} \Phi_n(1, \emptyset) \\ \vdots \\ \Phi_n(p, \emptyset) \end{bmatrix}$$

$$\sum_{k=1}^P \alpha_k \Phi_N(i, k) = \Phi_N(i, \emptyset)$$

$k \in [\emptyset, P] \quad i \in [1, P]$

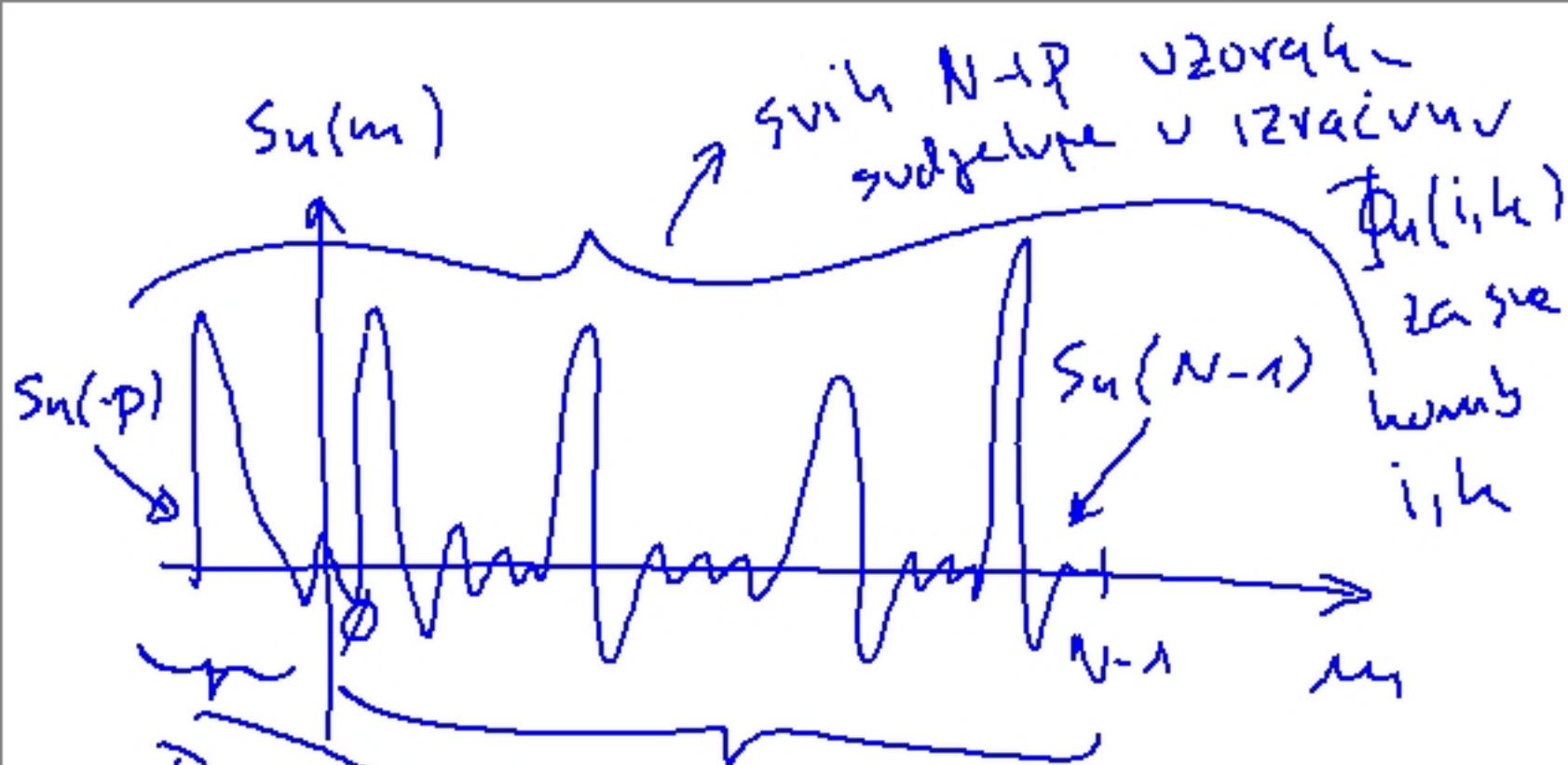
$k=1$ $N-1$ $i=1, 2, \dots, P$

$$\Phi_N(i, k) = \sum_{m=\emptyset}^{N-1-i} S_N(m-i) S_N(m+k)$$

$m = m'$ $m = m'+i$

$$\Phi_N(i, k) = \sum_{m'=-i}^{N-1-k} S_N(m') S_N(m'+(i-k))$$

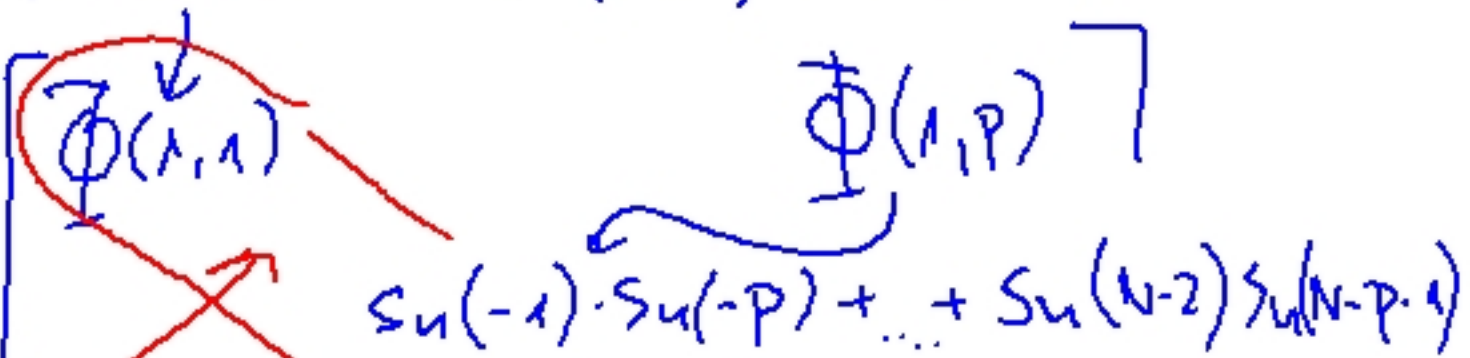
$$\Phi_N(i, k) = \sum_{m'=-k}^{N-1-i} S_N(m') S_N(m'+(k-i))$$



P uzoraka iz prošlosti olakša minimizaci.

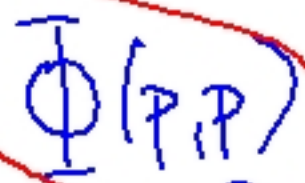
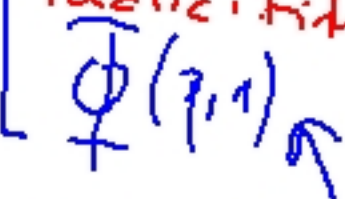
Ovo je dio gdje se minimizira E_n
 $[0 \dots N-1]$

$$S_u(-1) \cdot S_u(-1) + \dots + S_u(N-2) S_u(N-2)$$



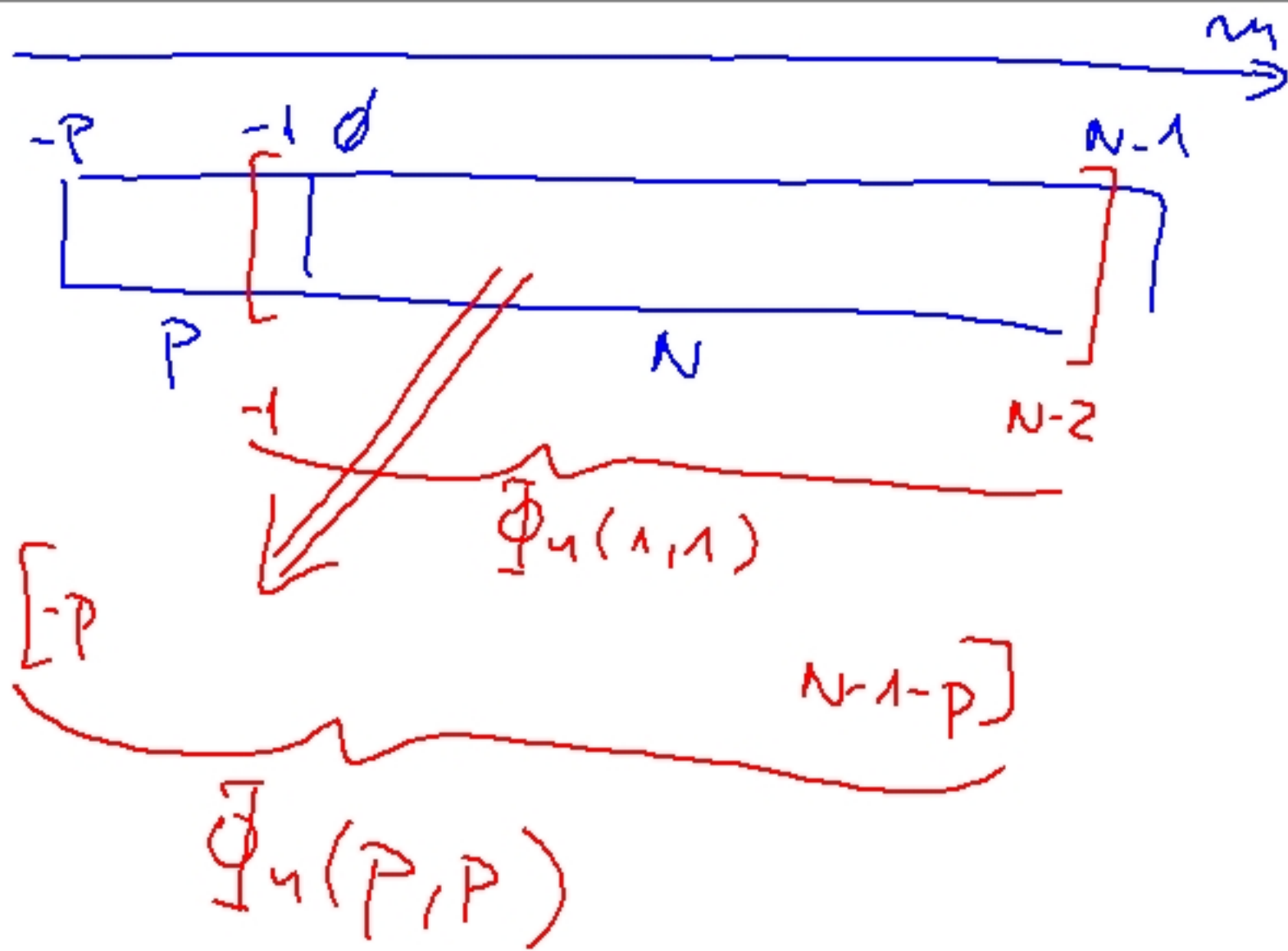
energije

N susjednih uzoraka
uz p različitih pomaka
u vremenu



$$S_u(-p) \cdot S_u(-1) + \dots + S_u(N-p-1) S_u(N-2)$$

$$S_u(-p) \cdot S_u(-p) + \dots + S_u(N-p-1) S_u(N-p-1)$$



$$\Phi_n(2,1) =$$

višak u jorupen

$$S_n(-2) \cdot S_n(-1) + \dots + S_n(N-3) S_n(N-2)$$

$$\Phi_n(3,2) =$$

višak u ovom izrazu

$$S_n(-3) S_n(-2) + S_n(-2) \cdot S_n(-1) + \dots + S_n(N-4) (N-3)$$

$$\Phi_u(3,2) = \Phi_u(2,1)$$

$$- S_u(N-3) S_u(N-2)$$

$$+ S_u(-3) S_u(-2)$$

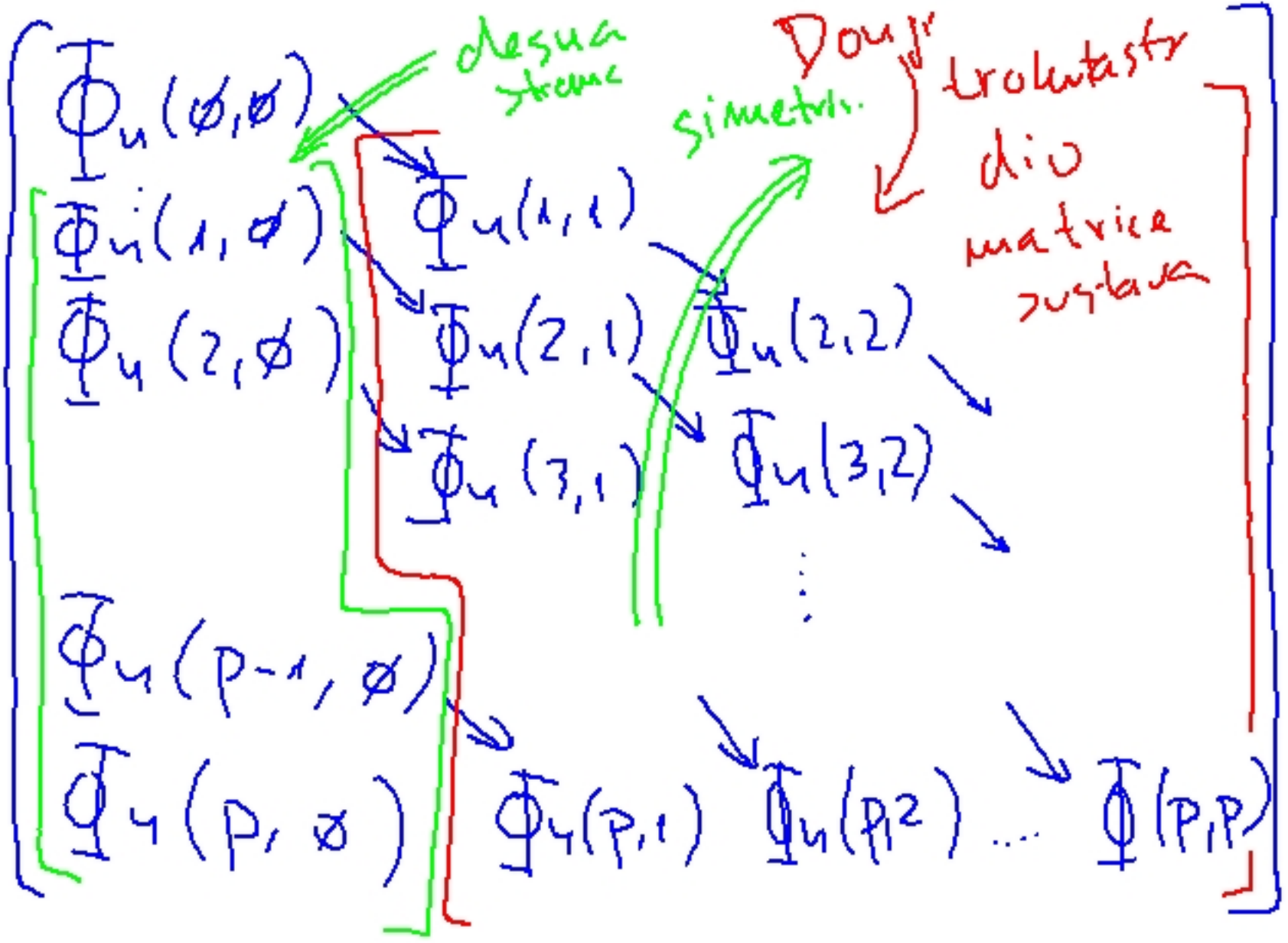

$$\Phi_u(i, k) \longleftrightarrow \Phi_u(i+1, k+1)$$

$$\Phi_u(i+1, k+1) =$$

$$\Phi_u(i, k) -$$

$$- S_u(N-(i+1)) S_u(N-(k+1))$$

$$+ S_u(-i-1) S_u(-k-1)$$



za određ. svih elemenata sistema

mat.:

$\Phi_n(i, \emptyset)$ ← direktni izraz
za $i \in [\emptyset, P]$

na osnovu $\Phi_n(\emptyset, \emptyset) \dots \Phi_n(P-1, \emptyset)$

odredi $\Phi_n(1, 1) \dots \Phi_n(P, 1)$

na osnovu
itd.

prvi stupac mat.
1. st odredi: 2. st

↘ rekursivni izraz

Broj operacija za elemente koji
se određuju direktnim izrazom:

$$(p+1) (N \text{ množenje} + (N-1) \text{ zbrajanje})$$

za svaki preostali element
rekurzivni izraz traži:

$$B = A - \underset{\substack{\uparrow \\ 2z}}{(0 \cdot 0)} + \underset{\substack{\uparrow \\ 2M}}{(0 \cdot 0)}$$

takvih ima $\sim p^2/2$

Reš. sustav

$$\Phi \cdot \alpha = \Psi \leftarrow \text{slab. stup.}$$

mat.
sustav

Φ simet. pozit. semi
definitna mat

Sve vlast. uv. ≥ 0

→ proizlazi iz strukture ujemih elem.
za takve sustave.

⇒ mogu se koristiti postupake metode
Cholesky dekompozicije (∇)

Matrica Φ se rastavlja na produkt
tri matrice:

$$\Phi = V D V^T$$

V donja trokutasta matrica sa
jedinicom na dijagonalom

$\leftarrow P_1$

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ V_{21} & 1 & 0 & 0 \\ V_{31} & V_{32} & 1 & 0 \\ V_{41} & V_{42} & V_{43} & 1 \end{bmatrix}$$

D je dijagonalna
matrica

$$\begin{bmatrix} d_1 & & \\ & \ddots & \\ & & d_n \end{bmatrix}$$

$$\Phi \alpha = \Psi$$



$$V \cdot D V^T \alpha = \Psi$$

řešim:

$$D V^T \alpha = \Psi$$

$$V^T \alpha = D^{-1} \Psi$$

pomocí vektor y

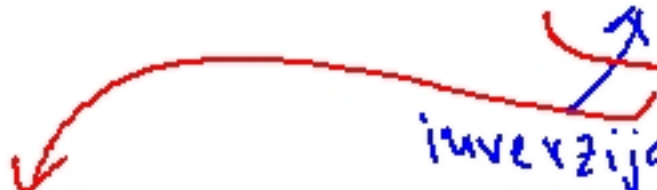
$$V \cdot y = \Psi$$

\Rightarrow odvedim y

$$\begin{bmatrix} y_n/d_n \\ \vdots \\ y_p/d_p \end{bmatrix}$$

$$\begin{bmatrix} 1/d_n & & \\ & \dots & \\ & & 1/d_p \end{bmatrix}$$

inverze dij. mat



$$\begin{bmatrix}
 1 & & & \\
 V_{21} & 1 & & \\
 V_{31} & V_{32} & 1 & \\
 V_{41} & V_{42} & V_{43} & 1
 \end{bmatrix}
 \begin{bmatrix}
 Y_1 \\
 \vdots \\
 Y_4
 \end{bmatrix}
 =
 \begin{bmatrix}
 \Psi_1 \\
 \vdots \\
 \Psi_4
 \end{bmatrix}$$

$V \cdot Y = \Psi$
 lako V_j

$$\begin{aligned}
 Y_1 &= \Psi_1 \\
 V_{21} \cdot Y_1 + Y_2 &= \Psi_2 \quad \Rightarrow \quad Y_2 = \Psi_2 - V_{21} Y_1 \\
 V_{31} Y_1 + V_{32} Y_2 + Y_3 &= \Psi_3 \quad \Rightarrow \quad Y_3
 \end{aligned}$$

$$\begin{bmatrix} 1 & 0 & 0 \\ V_{21} & 1 & 0 \\ V_{31} & V_{32} & 1 \end{bmatrix} \begin{bmatrix} d_1 \\ d_2 \\ d_3 \end{bmatrix} \begin{bmatrix} 1 & V_{21} & V_{31} \\ 0 & 1 & V_{32} \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} d_1 & 0 & 0 \\ d_1 V_{21} & d_2 & 0 \\ d_1 V_{31} & d_2 V_{32} & d_3 \end{bmatrix} \begin{bmatrix} - \\ - \\ - \end{bmatrix}$$

$$\Phi = \begin{bmatrix} d_1 & d_1 V_{21} & d_1 V_{31} \\ d_1 V_{21} & d_1 V_{21}^2 + d_2 & d_1 V_{21} V_{31} + d_2 V_{32} \\ d_1 V_{31} & d_1 V_{31} V_{21} + d_2 V_{32} & d_1 V_{31}^2 + d_2 V_{32}^2 + d_3 \end{bmatrix}$$

$$\Phi_n(i, k) = \sum_{j=1}^k V_{ik} d_j V_{kj}$$

zadnji član sumo

$$1 \leq k \leq i-1$$

$$= V_{ik} \cdot d_k \cdot \underbrace{V_{kk}}_{\substack{\text{diag. el.} \\ \text{matrix } V} = 1} + \sum_{j=1}^{k-1} V_{ik} d_j V_{kj}$$

deca. A za

$$V_{ik} \cdot d_k = \Phi_n(i, k) - \sum_{j=1}^{k-1} V_{ik} d_j V_{kj}$$

$$1 \leq k \leq i-1$$

za dijag. el. mat. Φ

$$\Phi_{[n]}(i,i) = \sum_{j=1}^i v_{ij} d_j v_{ij}$$

$$= \underbrace{v_{ii}}_{=1} d_i \underbrace{v_{ii}}_{=1} + \sum_{j=1}^{i-1} v_{ij} d_j v_{ij}$$

izmat \mathbb{R}

$$d_i = \Phi_{[n]}(i,i) - \sum_{j=1}^{i-1} v_{ij}^2 d_j \quad i=1, \dots, p$$

Spec. za $i=1$ $d_1 = \Phi_{[n]}(1,1)$

1. izraz $B \dots$ određuju d_1

$$d_1 = \Phi_n(1,1)$$

2. izraz $A \dots$ $V_{i,1}$ za $i=2 \dots p$

$$V_{i,1} \cdot d_1 = \Phi_n(i,1) - \sum_{j=1}^{i-1} V_{i,j} d_j V_{i,j}$$

← $k=1$
→ $k=i$

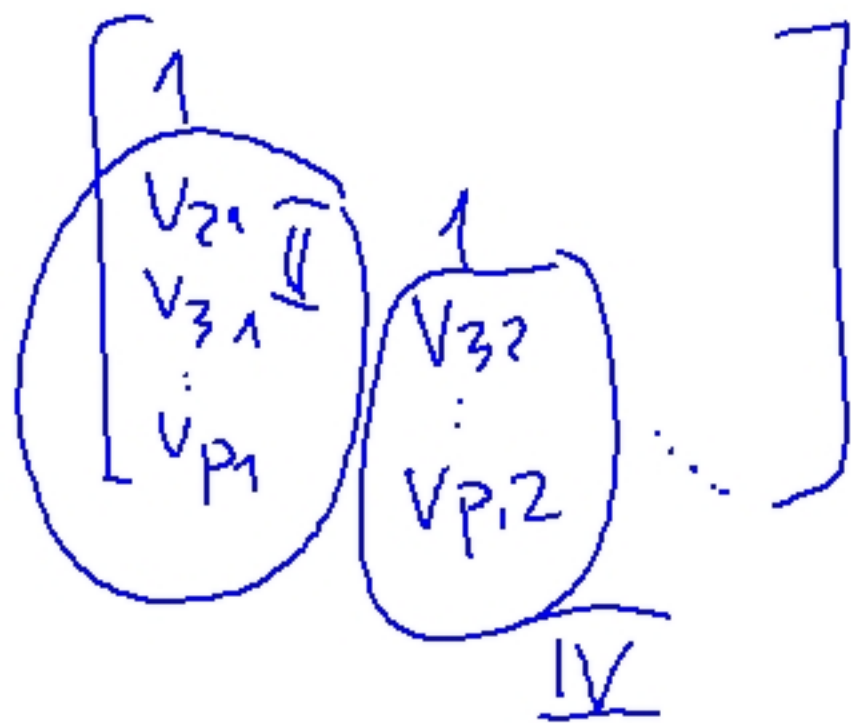
ne postoji.

$$V_{i,1} = \Phi_n(i,1) / d_1$$

$$V_{2,1} = \Phi_n(2,1) / d_1$$

$$V_{3,1} = \Phi_n(3,1) / d_1$$

iz prvog stupca mat. \underline{d}
 i odredimo elemente d_1
 odredjenom 1. st. mat. V



ponoiv izraza Φ
 odvedjemo d_2

$$d_2 = \Phi_{22} - V_{21}^2 d_1$$

\swarrow \searrow
 maier

\Rightarrow primyemo izraza A
 odvedjemo $V_{i,2} \quad i = k+1..P$

$$V_{3,2} \cdot d_2 = \Phi_{32} - \underbrace{V_{31} d_1 \cdot V_{21}}_{\text{maier}}$$

\swarrow
 $\Rightarrow V_{32}$

$$E_u = \Phi_u(\phi, \psi) - \sum_{k=1}^P \alpha_k \cdot \Phi_u(k, \phi)$$

$$E_u = \Phi_u(\phi, \psi) - \alpha^T \cdot \psi$$

$$D \cdot V^T \cdot \alpha = y \quad \text{II system.}$$

$$V^T \cdot \alpha = D^{-1} \cdot y$$

$$\alpha^T \cdot V = y^T \cdot \underbrace{(D^{-1})^T}_{= D^{-1}}$$

$$\alpha^T \cdot V = y^T \cdot D^{-1}$$

$$\alpha^T = y^T \cdot D^{-1} \cdot V^{-1}$$

$$E_u = \Phi_u(\rho, \phi) - \alpha^T \cdot \Psi = \Phi_u(\rho, \phi) - \sum_{i=1}^p \frac{y_i^2}{d_i} - \gamma^T D^{-1} \cdot V^{-1} \cdot \Psi$$

1. system red.

$$V \cdot y = \Psi$$

$$y = V^{-1} \cdot \Psi$$

$$\frac{y_1^2}{d_1} + \frac{y_2^2}{d_2} \dots \frac{y_p^2}{d_p}$$

$$= -\gamma^T \cdot D^{-1} \cdot y$$

$$[y_1 \dots y_p] \begin{bmatrix} d_1^{-1} \\ \vdots \\ d_p^{-1} \end{bmatrix} [y_p]$$

vrijedn Δ
za sve v
uize
red.